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consulted with an expert in the field. Another innovative information presented in this paper is to create procedures identifying defects described in chapter 4. Information contained in chapter 5 and 6 are supplementary, which are described in the previously presented publications, but it can not be ignore because of the whole defects identification process which is described in Fig. 1 (which figure is also innovative elaboration). The various stages shown in this diagram have been partially described already in published by the team positions, nevertheless such comprehensive approach to defects diagnostics hasn't been presented yet.

2. The structure of diagnostic processes

The problem of the design and implementation of diagnostic systems is still open, because for each application area, different solutions are needed,

particularly as regards the choice of formalisms of knowledge representation and decision algorithms, tailored to the user's specific needs.

In the approach proposed here, the following stages can be distinguished:

- identification of the type (name) of defect based on knowledge representation in the form of attribute table;
- identification of the causes of defect using knowledge representation and allowing for its incomplete and uncertain character;
- identification of the methods to prevent defects using knowledge acquired from diffuse and heterogeneous sources.

The breakdown of the diagnostic process into the above mentioned steps enables serialisation of the asked queries in a logical sequence, which directs the user's way of thinking, helping him to find adequate answers. Fig. 1 illustrates these steps.

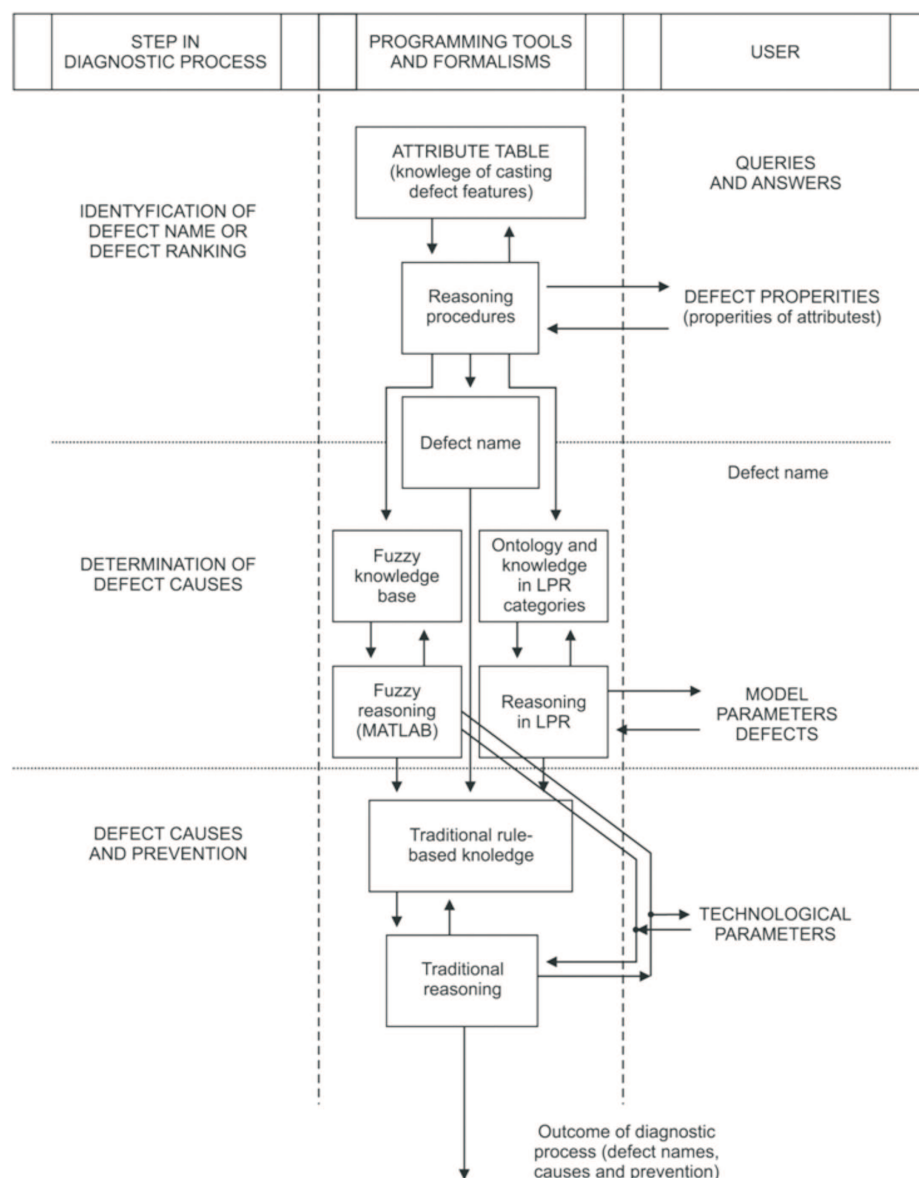


Fig. 1. Schematic diagram of the process of defect diagnosis

In any case, the starting point for the process of diagnosis is identification of the type (name) of defect. In this study, in the solution proposed and described in the present paper, this step has been implemented based on the attribute Table.

If user declares that he knows the name of the defect, direct transition to the second step follows, i.e. determination of the causes of defect occurrence.

There are three possibilities (variants) here:

- 1) User has sufficiently precise information about the parameters of the technological process, which allows direct transition to step 3, i.e. to a combined determination of the causes of defects and means to prevent their occurrence.
- 2) User's knowledge of the technological parameters is of approximate and uncertain character. Then it is recommended to use the solutions based on fuzzy logic, which result in a determination of the likely causes of defects or in a ranking of possible causes.
- 3) User's knowledge is of an intuitive character and relates to certain relationships and linkages that exist in the process rather than to the specific values of various parameters. In this situation, it is proposed to apply the logic of plausible reasoning (LPR).
- 4) The last step in the diagnostic procedure is indication of the diagnostic measures to prevent the occurrence of a given type of defect. This action can be preceded by an indication of the cause of defect.

3. Attribute Table

The concept that was adopted in creation of this module resulted from several important tasks that it should satisfy:

- 1) provide the ability to integrate knowledge from different (possibly heterogeneous) sources;
- 2) provide the ability to create dialogue procedures, tailored to the user's needs and competencies;
- 3) provide the ability to use incomplete and uncertain knowledge;
- 4) provide options for application of the reasoning procedures forming a flexible interpretation of the existing knowledge, at different levels of generality.

It should be noted that in the proposed solution the starting point for the creation of an attribute table are casting defect classification systems, described in standards, directories, and national and international handbooks. The need for an ability to integrate knowledge from different sources results from the fact that in various systems of classification there are different divisions into classes, groups and names of the defects. Below, systems used in this study have been depicted graphically and briefly characterised.

Figure 2 shows the system based on a French method of classification published in the atlas of defects. [1, 2] This division is of a very complex nature. The classes of defects are designated with capital letters from A to G. Each class comprises several groups of defects (e.g. A100, A200, A300), these, in turn, comprise subgroups (e.g. A110, 120...), subgroups include defects designated with a letter that denotes the class of defect they belong to, and a three-digit number that denotes their membership in group and subgroup. (e.g. A111, A112, A113...).

		French system
Metallic build-up A	A100 Thin-layer metallic build-up A200 Massive build-up A300 Other metallic build-up forms	
Cavities B	B100 Cavities of round and smooth walls, easily recognisable and visible to naked eye (blowholes and pinholes) B200 Cavities of rough walls. Shrinkage cavities B300 Areas with numerous porosities, spongy and with clusters of cavities	
Discontinuities C	C100 Discontinuities caused by mechanical damage (breakout), usually of sharp edges. Casting shape and appearance of fracture do not indicate the presence of internal stresses C200 Hot cracks C300 Discontinuities caused by cold shuts (cold laps), usually of rounded edges, indicate incorrect running of different metal jets during mould filling C400 Discontinuities caused by metallurgical defects	
Surface defects D	D100 Surface defects D200 Relatively large irregularities on casting surface Stosunkowo duże nieregularności na powierzchni odlewu	
Incomplete casting E	E100 Misrun E200 Mechanical damage	
Incorrect dimension F	F100 Incorrect dimension but correct shape F200 Incorrect shape of the whole casting or of some parts	
Inclusions and incorrect structure G	G100 Inclusions G200 Incorrect structure (visible in macroscopic examination)	

Fig. 2. The division of defects into classes, groups and names according to a French system


		Polish system	
Shape incorrectness	Surface defects	Discontinuities	Internal defects
W 100	W 200	W 300	W 400
W-101 Mechanical damage	W-201 Roughness	W-301 Hot crack	W-401 Blowhole
W-102 Misrun	W-202 Surface blow	W-302 Cold crack	W-402 Porosity
W-103 Knob	W-203 Pitted skin	W-303 Hot tear	W-403 Shrinkage cavity
W-104 Flash	W-204 Orange skin	W-304 Annealing crack	W-404 Shrinkage porosity
W-105 Mismatch	W-205 Pinholes	W-305 Intercrystalline crack	W-405 Slag inclusions
W-106 Swell	W-206 Shrinkage depressions		W-406 Sand inclusions
W-107 Warping	W-207 Cold lap		W-407 Cold shots
	W-208 Scab		W-408 Metallic inclusions
	W-209 Rattail		W-409 Segregation
	W-210 Sand holes		W-410 Coarse grain structure
	W-211 Crush		W-411 Hard spots
	W-212 Unclean surface		W-412 Grey spots
	W-213 Scale		W-413 White fracture
	W-214 Seizure		W-414 Bright fracture
	W-215 Partial melting		W-415 Bright border
	W-216 Elephant skin		W-416 Heterogeneous material
	W-217 Sweat		
	W-218 Flowers		
	W-219 Metal penetration		
	W-220 Veining		
	W-221 Burn-on		
	W-222 Sand holes		
	W-223 Oxidation		
	W-224 Peeling		

Fig. 3. The division of defects into classes and names according to a Polish system

The classification in Fig. 3 is a system described in Polish Standard PN 85/H-83105 [3]. According to this system, the defects are divided into 4 classes designated with the following symbols: W-100, W-200, W-300, W400. To each class belong the defects designated with letter W and a three-digit number denoting the class number (e.g. W 206, W-107, W 301);

		Czech system
100	Incorrect shape, size and weight	
110	Missing part of casting without fracture	111 112 113 114 115 116 117
120	Missing part of casting with fracture	121 122 123
130	Inaccuracy of dimensions, incorrect shape	131 132 133 134
140	Inaccuracy of casting weight	
200	Surface defects	
210	Burn-on	211 212 213
220	Rat-tails	221 222 223
230	Scabs	231 232 233 234
240	Veining	
250	Sweat	
260	Flashes	261 262 263
270	Surface irregularities	271 272 273 274 275 276 277
280	Defects in surface protection	

Fig. 4. The division of defects into classes, groups and names according to a Czech system

The system shown in Fig. 4 was developed in the Czech Republic [4]. According to this system, the defects are divided in 7 classes designated with three-digit numbers (e.g. 100, 200...), each class is divided further into groups (110, 120, 130...), each group may include specific names of defects (111, 112, 113...), or sometimes the name of the group is also the name of the defect. As mentioned previously, conditions from 1 to 4 must be satisfied. The knowledge representation with attribute table (decision table) was used here, i.e. the method which has not been used until now in solutions of this type [5, 6].

Figure 5 shows a general form of an attribute table, where $A = \{A_1, A_2, \dots, A_n\}$, $\{D_1, D_2, \dots, D_n\}$ are domains, and D_i is the domain of attribute A_i for $(i=1, 2, \dots, n)$. The table is a finite set of names.

In the description of object properties (O_i), the values of all attributes or conditions that these objects should satisfy are given. An elementary notation of the fact which says that the value of attribute A_i for object O_j is t_i has the form $A_i = t_{ij}$, where $t_{ij} \subseteq D_i$ while $O_j \in \Omega$ (where: Ω - the set of all described objects). Owing to such notation, a significant extension compared to the classical relational data model is obtained. Attribute values need not be explicit, so the representation of the conditions to be met by individual attributes allows for an interval specification, or for a specification in the form of a set (of value or names). Figure 5 shows schematic representation of information. The columns of this table are the values of relevant attributes, while rows correspond to the descriptions of successive objects O_j ($j=1, \dots, k$), on which the rules are based.

A_1	A_2	A_3	...	A_i	O
$t_{1,1}$	$t_{1,2}$	$t_{1,3}$...	$t_{1,5}$	O_1
$t_{2,1}$	$t_{2,2}$	$t_{2,3}$...	$t_{2,5}$	O_2
...
$t_{i,1}$	$t_{i,2}$	$t_{i,3}$...	$t_{i,5}$	O_i
...
$t_{k,1}$	$t_{k,2}$	$t_{k,3}$...	$t_{k,5}$	O_k

Fig. 5. The structure of attribute table

Defect name	Damage type	Visibility	Damage size	Material loss/gain	Range	Location	Moulding material	Inclusions	Occurrence rate	Shape
121 Hot casting break off	breaking off	well visible	distinct	loss	local	surface	any	absent	single cases	insignificant
						edge				
		invisible to naked eye			spread	protruding elements				
122 Hot Cold casting break off Cz	breaking off	well visible	distinct	loss	local	surface	any	absent	single cases	insignificant
						edge				
		invisible to naked eye			spread	protruding elements				
320 Cracks Cz	crack	well visible	distinct	loss	local	wall	any	oxides	single cases	straight
						surface				zigzagged
										curved
331 Hot fracture Cz	crack	invisible to naked eye	small	insignificant	clusters	interior	any	absent		idefinite
						surface				

Fig. 6. Fragment of an attribute table with names of defects regardless of their classification system

It is assumed that objects are homogeneous, i.e. each of them is described by specifying the value of the same set of attributes (assuming that an attribute can have the zero value). The contents of the table can represent data (attribute values are independent), data patterns (attribute values are then subsets of the fields), and rules of inference.

The attribute table can be used in defect identification, based on attribute values specified in the table. Analysing the descriptions of defects included in the source documents [1,2,3,4], a list of the attributes of defects which occurred in any of the considered systems (sources) has been made. In this way, an attribute set A has been defined.

For each of these attributes, the respective domains (D_i) were defined. A complete attribute table includes 90 names of defects; to each of these defects, the attributes were ascribed in 18 columns (a fragment is shown in Fig. 6). These sets are not equinumerous, which means that the size of set D_i is not necessarily equal to the size of set D_j (e.g. for the attribute damage type 42 values were specified, while for the attribute size only 3 values were stated).

The essential difference between the traditional decision tables and attribute tables constructed in this study consists in this that the table proposed here has empty places.

It is worth noting that, directly from the table, one can obtain logical expressions defining the name of the defect as a conjunction of attribute values assigned to this defect.

$$\rho_i = [A_1 = t_{i,1}] \wedge [A_2 = t_{i,2}] \wedge \dots \wedge [A_n = t_{i,n}] \Rightarrow [O = o_i] \quad (1)$$

Thus, the rule specifies the name of the defect the attributes of which have the value $t_{i,1} \dots t_{i,n}$. In practical interpretation, this rule in linguistic notation can, e.g., express the following statement:

$R_i = [\text{damage type} = \text{break off}] \wedge [\text{visibility} = \text{well visible}] \wedge [\text{range} = \text{local}] \wedge [\text{location} = \text{surface}] \wedge [\text{moulding material} = \text{any}] \wedge [\text{inclusions} = \text{absent}] \wedge [\text{occurrence rate} = \text{single forms}] \wedge [\text{defect shape} = \text{insignificant}] \wedge [\text{cast material} = \text{any}] \wedge [\text{penetration} = \text{surface}] \wedge [\text{surface colour} = \text{metal colour}] \wedge [\text{orientation} = \text{insignificant}] \wedge [\text{surface oxidation} = \text{oxidised}] \wedge [\text{defect surface} = \text{data not available}] \wedge [\text{moment of defect formation (process stage)} = \text{mechanical fettling of casting}] \Rightarrow \text{hot casting break off}.$

(2)

Rules of the structure corresponding to expression (1) can be formed directly from the rows of attribute table.

At the same time, attention deserves the fact that, using the table, one can formulate rules of more complex structure regarding, e.g., indication of a group of defects or equivalence with defects described by other standards.

Figure 7 shows block diagram of the application implementing the defect identification procedure based on the knowledge contained in an attribute table.

Below an algorithm of defect identification is presented. To facilitate the interpretation of this algorithm in terms of technology, a descriptive form was used to allow for comments on the successive stages of the procedure.

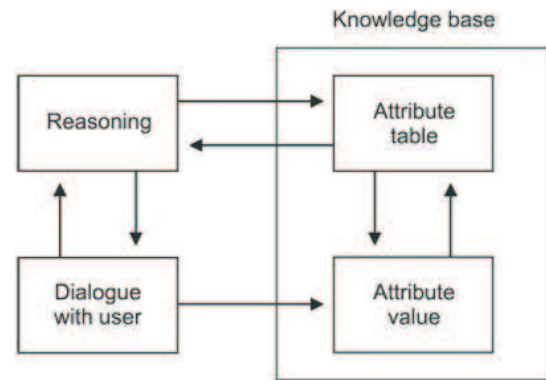


Fig. 7. Block diagram of pilot application

Initial state:

Knowledge base:

Attribute table $T^{m \times n}$

n-number of rows (rules)

m-number of columns (attributes)

Sets of attribute values V_j ($j=1 \dots m$).

$$\begin{aligned} V_1 &= (a_{11}, a_{12}, \dots, a_{1k_1}) \\ V_2 &= (a_{21}, a_{22}, \dots, a_{2k_2}) \\ &\dots \dots \dots \\ V_m &= (a_{m1}, a_{m2}, \dots, a_{mk_m}) \end{aligned} \quad (3)$$

It should be noted that the numerical values of individual attributes (k_1, k_2, \dots, k_m) are generally different.

4. Procedure for defect identification

The procedure consists in asking queries about the values of the successive attributes (a_{jk})

Step 1: Query: Give value of attribute a_1 from the set V_1

Answer : $a_1 = v_{1k}$

Reasoning : $T^{nm}(X(0), a_1 = v_{1k}) \rightarrow T^{\lambda(1)m}(X(1))$ (4)

where:

$X(1)$ – the set of objects (defects) for which the value of attribute a_1 is v_{1k}
that is

$\rho: (x_i, a_1) = v_{1k}, x_i \in X, 1, a_j \in A \text{ or } v_{1k} \in V_1$ (5)

$\lambda(1)$ – the number of objects satisfying condition (5).

So, as a result of the execution of the first step in an algorithm, the number of objects (defects) examined in further reasoning has been reduced and now is $\lambda(i)$, and not n as it was at the beginning.

Step 2: Query: Give value of attribute a_2 from the set V_2

Answer : $a_2 = v_{2l}$

Reasoning : $T^{\lambda(1),mm}[X(1), a_2 = v_{2l}] \rightarrow T^{\lambda(2),m}(X(2))$ (6)

where:

$X(2)$, $\lambda(2)$ – the set of objects and their number, respectively, obtained as a result of operation 6

.....
.....

Step m: Query: Give value of attribute a_m from the set V_m

Answer : $a_m = v_{m\tau}$

Reasoning : $T^{\lambda(m-1),m}[X(m-1), a_m = v_{m\tau}] \rightarrow T^{\lambda(m),m}(X(m))$ (7)

where:

$X(m)$ – the set of objects (defects) determined as a result of ascribing the values to all attributes $a_j \in A$.

At the end of the procedure, three cases can be distinguished:

1) If $X(m)$ is a singleton,

that is $\lambda(m)=1$, then the name of the defect is clearly indicated and the procedure is completed. However, compliance with this condition is the case rather theoretical. In practical situations, the following possibilities may occur:

2) Indication of specific defect may occur earlier, i.e. after the number of steps $k < m$, if by this time the $n-1$ objects (defect types) have already been eliminated. In other words, even stating the value of k attributes is enough to distinguish given object (defect) from all other attributes described in the attribute table.

3) Having ascribed values to all attributes, i.e. after m steps of the algorithm, the set $X(m)$ still holds more than one object. So, $\lambda(m) > 1$.

This corresponds to the situation when certain objects (defects) are described with the same values of attributes. This situation may occur when the same defect has different names (e.g. when knowledge comprised in standards or catalogues edited by different nations is used). This happens in the case of defect A in Polish classification, and defect B in French classification, as well as defect C in Czech classification.

5. Diagnosis of the causes of defects

To determine the causes of defects on the basis of incomplete and uncertain data, two types of logic have been used, viz. logic of plausible reasoning and fuzzy logic. The logic of plausible reasoning is used in those areas where knowledge about the causes of defect formation is of an intuitive character, most often “man-associated”. This logic is also used to connect the data on causes of defects originating from different sources. The problem has been described in reference literature [7].

For indefiniteness considered in two aspects, viz.:

- at the level of knowledge about the defect, which does not explicitly attribute to the defect the reasons of its occurrence;
- referred to the parameters of technological process (in the course of which the defect has occurred), usually determined in an approximate way;

a formalism was used which takes into account both the lack of precise knowledge about the defects, as well as an approximate nature of information about the parameters of the technological process.

The formalism, which by definition is dedicated to the description of such situations, is fuzzy logic [8, 9].

6. Determination of the method to prevent defect occurrence

This module has been based on bivalent logic. The formulation of rules in terms of bivalent logic consists in identification of causal-resultant relationship between the variables of values taken from the set $\{0,1\}$, with respective interpretation $\{\text{false}, \text{true}\}$.

A typical for expert systems procedure (applied, among others, in CastExpert system) consists in sequential application of rules. The course of the final diagnostic procedure can be represented as a schematic diagram shown in

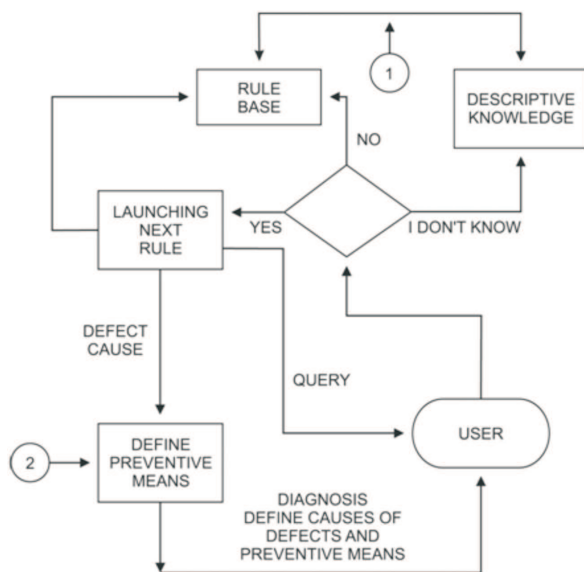


Fig. 8. Schematic diagram of final diagnostic procedure

Indicating the name of defect results in one of the rules being selected from the base. An answer to this query is meant to confirm the truth of the premises in the rule under consideration.

7. Summary

The entire system creates a consistent methodological approach, enabling more comprehensive treatment of the diagnostic process, what should be noted as a new solution of the problem. So far, discussed in the literature solutions were presented individually, while at the same time, the use of alternative solutions for module defining the causes of defects (fuzzy logic, LPR, classical logic) allows adaptation of decision-making procedures to current user's competences, and hence acting under the conditions of uncertainty.

All this results in increased efficiency and reliability of the diagnostic process. At the same time it must be acknowledged that the lack of actual data on the numerical characteristics of a technological process prevents the acquisition of assessments characterising the diagnostic process in a quantitative manner (in order to carry out such studies, data from

multiple cycles of casting are necessary). Therefore, out of necessity, the developed solutions could be verified basing only on the qualitative assessments made by experts and process engineers. The said assessments issued by the cooperating foundry plants were definitely favourable.

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